Interpretable Prototypes for Robot Manipulation

Project group "Praxis der Forschung"
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1 Projekt

Prototype Learning is an intrinsicly interpretable deep learning approach gaining new traction in recent years, especially in the field of computer vision. We want to explore several prototype approaches in the field of robot manipulation, e.g., by combining them with newly developed movement primitives formulations like ProDMP.

2 Kontakt

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