
Formal Specification of Software

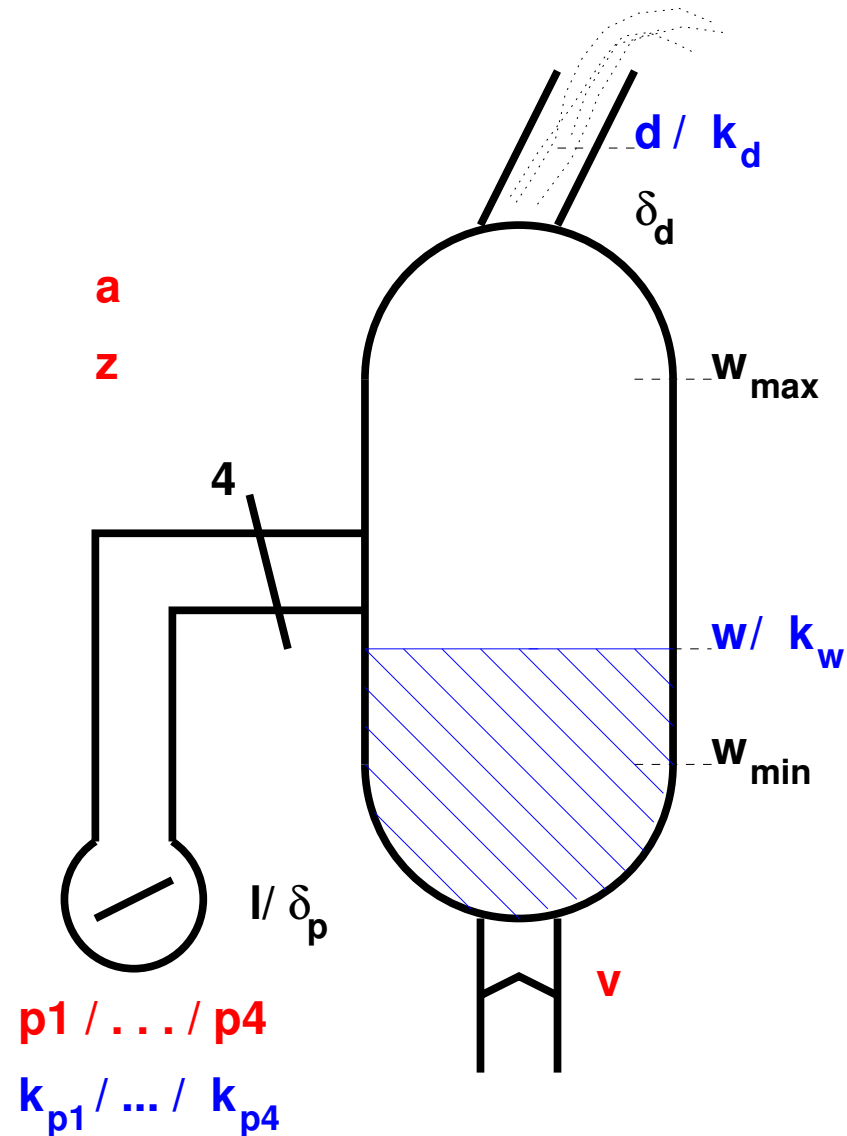
Steam Boiler Control
An Example in Z Formalisation

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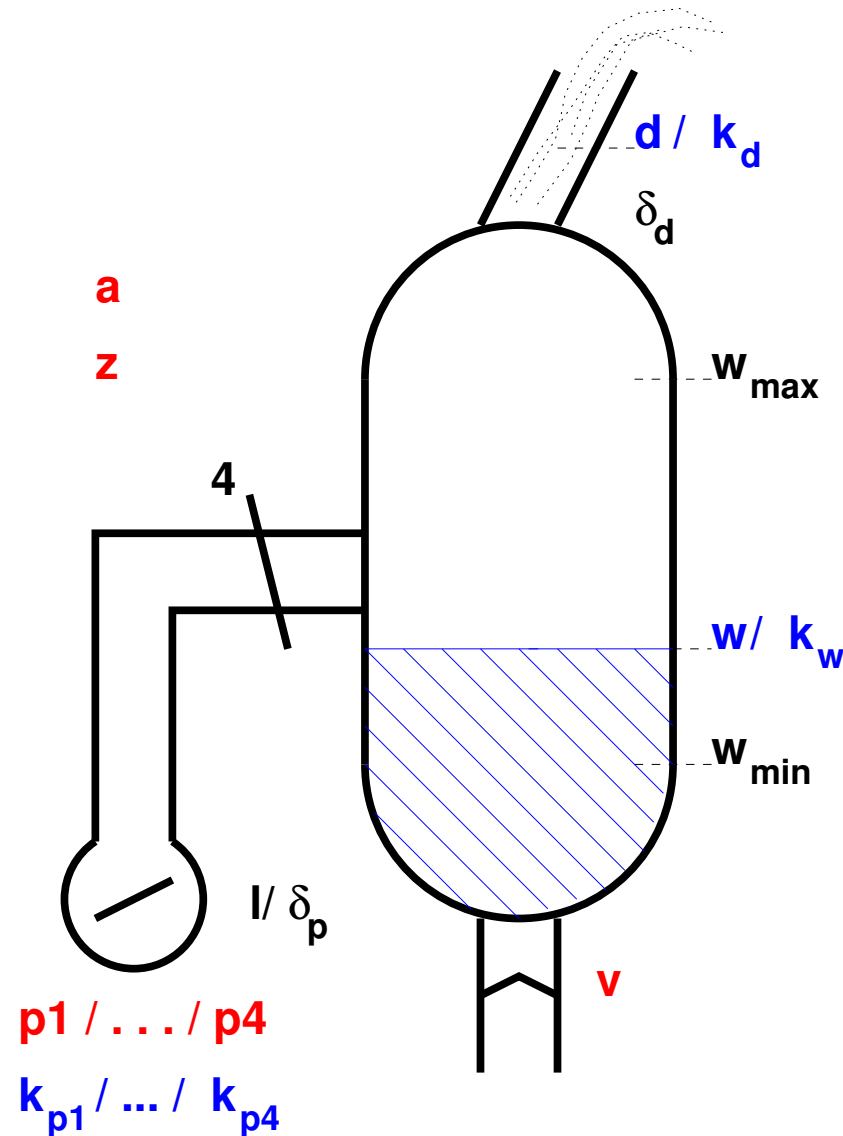
Steam Boiler Control: Scenario



System Components

- steam boiler
- water level measuring device
- four pumps
- four pump controllers
- steam quantity measuring device
- valve for emptying the boiler

Steam Boiler Control: Scenario



Physical constants

w_{min}

minimal water level

w_{max}

maximal water level

l

water amount per pu

d_{max}

maximal quantity of
exiting the boiler

δ_p

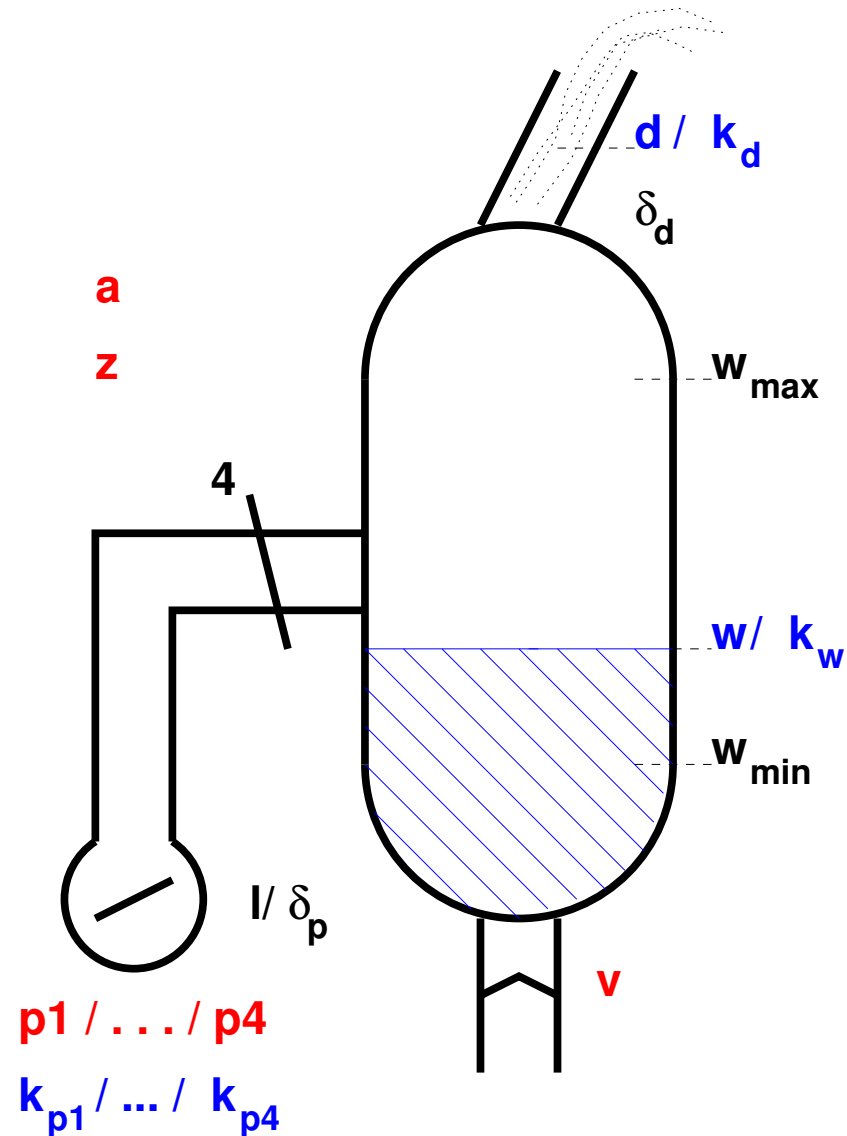
error in the value of

δ_d

error in steam

measurement

Steam Boiler Control: Scenario



Measured values

w water level

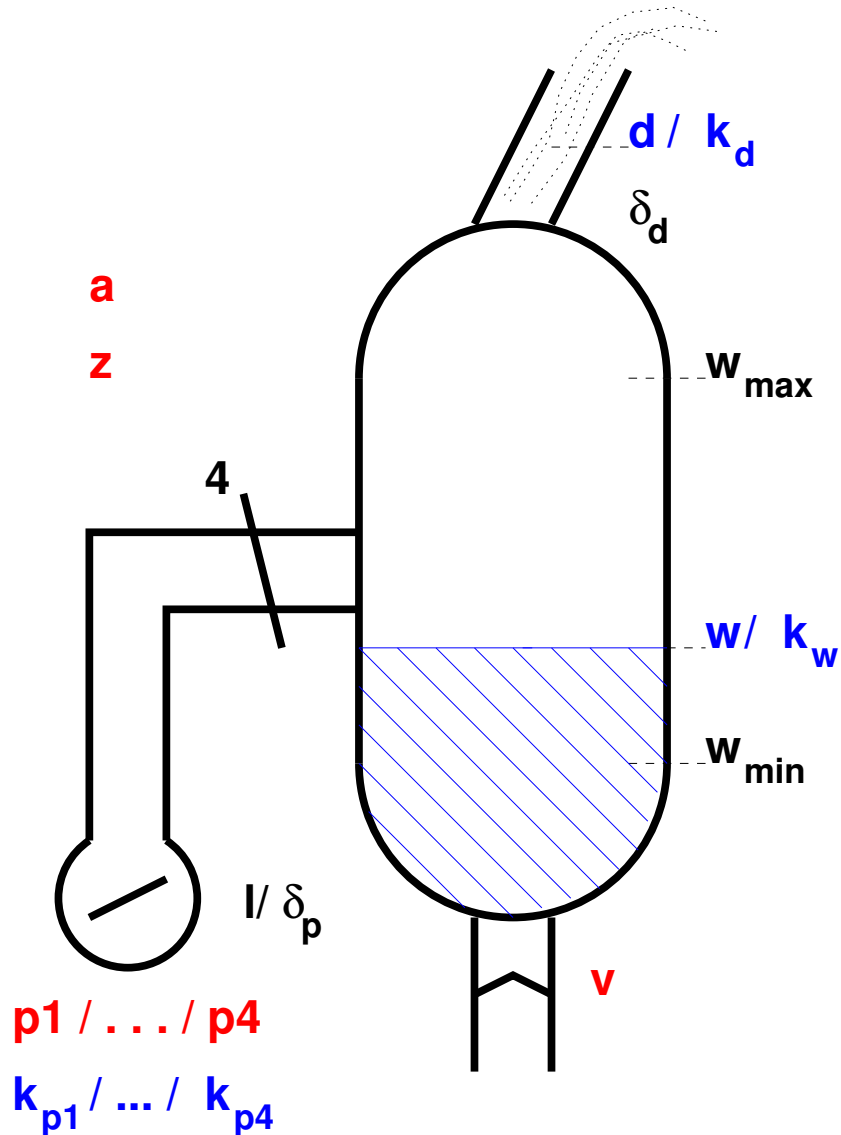
d amount of steam exiting
the boiler

$k_{p,i}$ pump i works/broken

k_w water level measuring device
works/broken

k_d steam amount measuring
device works/broken

Steam Boiler Control: Scenario



Control values

p_i pump i on/off

v valve open/closed

a boiler on/off

z state init/norm/broken/stop

Steam Boiler Control

Types

$State ::= init \mid norm \mid broken \mid stop$

$OnOff ::= on \mid off$

$OpenClosed ::= open \mid closed$

Steam Boiler Control

Physical constants

$$w_{min} : \mathbb{N}$$

$$w_{max} : \mathbb{N}$$

$$l : \mathbb{N}$$

$$d_{max} : \mathbb{N}$$

$$\delta_p : \mathbb{N}$$

$$\delta_d : \mathbb{N}$$

$$w_{min} < w_{max}$$

Steam Boiler Control

Physical constants

$w_{min} : \mathbb{N}$

$w_{max} : \mathbb{N}$

$l : \mathbb{N}$

$d_{max} : \mathbb{N}$

$\delta_p : \mathbb{N}$

$\delta_d : \mathbb{N}$

$w_{min} < w_{max}$

Measured values

Input

$w? : \mathbb{N}$

$d? : \mathbb{N}$

Steam Boiler Control

Control values

Pumps

$p_1, p_2, p_3, p_4 : OnOff$

SteamBoiler0

Pumps

$v : OpenClosed$

$a : OnOff$

$z : State$

Auxiliary Schemata

Auxiliary Schemata

PumpsOff _____

Pumps'

$$p'_1 = \text{off} \wedge p'_2 = \text{off} \wedge p'_3 = \text{off} \wedge p'_4 = \text{off}$$

PumpsOn _____

Pumps'

$$p'_1 = \text{on} \wedge p'_2 = \text{on} \wedge p'_3 = \text{on} \wedge p'_4 = \text{on}$$

Steam Boiler Initial State

SteamBoilerInit0

SteamBoiler0'

a' = off

z' = init

Operations for Initialisation

SInitNormal0

ΔSteamBoiler0

Input

$z = \text{init}$

$d? = 0$

$w? \geq w_{\min} + d_{\max}$

$w? \leq w_{\max}$

PumpsOff

$z' = \text{norm}$

$v' = \text{closed}$

$a' = \text{on}$

Operations for Initialisation

SInitStop0

Δ *SteamBoiler0*

Input

$z = \textit{init}$

$d? > 0$

$z' = \textit{stop}$

Operations for Initialisation

SInitFill0

Δ *SteamBoiler0*

Input

$z = \textit{init}$

$d? = 0$

$w? < w_{\min} + d_{\max}$

PumpsOn

$z' = z$

$v' = \textit{closed}$

$a' = \textit{off}$

Operations for Initialisation

SInitEmpty0

ΔSteamBoiler0

Input

z = init

d? = 0

w? > w_{max}

PumpsOff

z' = z

v' = open

a' = off

Operations for Initialisation

$$\begin{aligned} \textit{ControlInit0} &\hat{=} && \textit{SInitNormal0} \\ & && \vee \textit{SInitStop0} \\ & && \vee \textit{SInitFill0} \\ & && \vee \textit{SInitEmpty0} \end{aligned}$$

Operations for Normal State

SNormalFill0

ΔSteamBoiler0

Input

$z = norm$

$w? \geq w_{min}$

$w? \leq w_{opt} - 3l$

PumpsOn

$v' = closed \wedge a' = on \wedge z' = z$

Note:

Simplified version where all four pumps are switched simultaneously

Operations for Normal State

SNormalContinue0

⊢SteamBoiler0

Input

$z = \text{norm}$

$w? > w_{opt} - 3l$

$w? \leq w_{opt}$

Operations for Normal State

SNormalNotFill0

ΔSteamBoiler0

Input

$z = \text{norm}$

$w? > w_{opt}$

$w? \leq w_{max}$

PumpsOff

$v' = \text{closed} \wedge a' = \text{on} \wedge z' = z$

Operations for Normal State

SNormalStop0

ΔSteamBoiler0

Input

$z = norm$

$w? < w_{min} \vee w? > w_{max}$

$a' = off \wedge z' = stop$

Complete Operation

$$\begin{aligned} \text{ControlNormal0} &\hat{=} \text{SNormalFill0} \\ &\vee \text{SNormalContinue0} \\ &\vee \text{SNormalNotFill0} \\ &\vee \text{SNormalStop0} \end{aligned}$$

$$\begin{aligned} \text{Control0} &\hat{=} \text{ControlInit0} \\ &\vee \text{ControlNormal0} \end{aligned}$$

Extended Solution

Additional Type

$WorksBroken ::= works \mid broken$

Extended Solution

Additional Type

$WorksBroken ::= works \mid broken$

Additional measured values

ControlInput

$k_w? : WorksBroken$

$k_d? : WorksBroken$

$k_{p1}? : WorksBroken$

$k_{p2}? : WorksBroken$

$k_{p3}? : WorksBroken$

$k_{p4}? : WorksBroken$

Extended Solution

Control values

SteamBoiler1

SteamBoiler0

$s : \mathbb{N}$

$\delta : \mathbb{N}$

Extended Solution

Control values

SteamBoiler1

SteamBoiler0

$s : \mathbb{N}$

$\delta : \mathbb{N}$

Initial State

SteamBoilerInit1

SteamBoiler1'

$a' = \text{off}$

$z' = \text{init}$

Extended Auxiliary Schemata

Auxiliary Functions

$$pswitch : (OnOff \times WorksBroken) \rightarrow OnOff$$
$$pswitch(on, works) = on$$
$$pswitch(on, broken) = off$$
$$pswitch(off, works) = off$$
$$pswitch(off, broken) = off$$
$$pamount : (OnOff \times WorksBroken) \rightarrow \mathbb{N}$$
$$\forall x : OnOff, y : WorksBroken$$
$$| x = off \vee y = broken \bullet pamount(x, y) = 0$$
$$pamount(on, works) = 1$$

Extended Auxiliary Schemata

Auxiliary Schemata

PumpsControlledOn

Pumps'

ControlInput

$$p'_1 = pswitch(on, k_{p1}?) \wedge p'_2 = pswitch(on, k_{p2}?)$$

$$p'_3 = pswitch(on, k_{p3}?) \wedge p'_4 = pswitch(on, k_{p4}?)$$

PumpsControlledOff

Pumps'

ControlInput

$$p'_1 = pswitch(off, k_{p1}?) \wedge p'_2 = pswitch(off, k_{p2}?)$$

$$p'_3 = pswitch(off, k_{p3}?) \wedge p'_4 = pswitch(off, k_{p4}?)$$

Operations for Initialisation

SInitNormal1

ΔSteamBoiler1

Input

ControlInput

$z = \text{init}$

$d? = 0$

$k_w = \text{works} \wedge k_d = \text{works}$

$w? \geq w_{\min} + d_{\max}$

$w? \leq w_{\max}$

$z' = \text{norm}$

$v' = \text{closed}$

$a' = \text{on}$

$s' = w?$

PumpsOff

Operations for Initialisation

SInitFill1

ΔSteamBoiler1

Input

ControlInput

$z = \text{init}$

$d? = 0$

$k_w = \text{works} \wedge k_d = \text{works}$

$w? < w_{\min} + d_{\max}$

$z' = z$

$v' = \text{closed}$

$a' = \text{off}$

PumpsOn

Operations for Initialisation

SInitEmpty1

ΔSteamBoiler1

Input

ControlInput

$z = \text{init}$

$d? = 0$

$w? > w_{\max}$

$z' = z$

$v' = \text{open}$

$a' = \text{off}$

PumpsOff

Operations for Initialisation

SInitStop1

ΔSteamBoiler1

Input

ControlInput

z = init

d? > 0 ∨ k_w = broken ∨ k_d = broken

z' = stop

Operations for Initialisation

$$\begin{aligned} \text{ControlInit1} &\hat{=} && \text{SInitNormal1} \\ & && \vee \text{SInitFill1} \\ & && \vee \text{SInitEmpty1} \\ & && \vee \text{SInitStop1} \end{aligned}$$

Operations for Normal State

SNormalFill1

ΔSteamBoiler1

Input

ControlInput

$z = \text{norm}$

$k_w = \text{works}$

$w? \geq w_{\min}$

$w? \leq w_{\text{opt}} - 3l$

$s' = w?$

PumpsControlledOn

$v' = \text{closed} \wedge a' = \text{on} \wedge z' = z$

Operations for Normal State

SNormalContinue1

ΔSteamBoiler1

Input

ControlInput

$z = \text{norm}$

$k_w = \text{works}$

$w? > w_{opt} - 3l$

$w? \leq w_{opt}$

$p'_1 = \text{pswitch}(p_1, k_{p1}) \wedge p'_2 = \text{pswitch}(p_2, k_{p2})$

$p'_3 = \text{pswitch}(p_3, k_{p3}) \wedge p'_4 = \text{pswitch}(p_4, k_{p4})$

$s' = w?$

$v' = v \wedge a' = a \wedge z' = z$

Operations for Normal State

SNormalNotFill1

ΔSteamBoiler1

Input

ControlInput

$z = \text{norm}$

$k_w = \text{works}$

$w? > w_{\text{opt}}$

$w? \leq w_{\text{max}}$

$s' = w?$

PumpsControlledOff

$v' = \text{closed} \wedge a' = \text{on} \wedge z' = z$

Operations for Normal State

SNormalWaterStop1

ΔSteamBoiler1

Input

ControlInput

$z = \text{norm} \vee z = \text{broken}$

$k_w = \text{works}$

$w? < w_{\min} \vee w? > w_{\max}$

$a' = \text{off} \wedge z' = \text{stop}$

Operations for Normal State

SNormalControlStop1

ΔSteamBoiler1

Input

ControlInput

z = norm

k_w = broken ∧ k_d = broken

a' = off ∧ z' = stop

Schema *AmountComputation*

AmountComputation

SteamBoiler1

ControlInput

amount : \mathbb{N}

δ_{pumps} : \mathbb{N}

$$amount = l * (pamount(p_1, k_{p1}?) + pamount(p_2, k_{p2}?) + pamount(p_3, k_{p3}?) + pamount(p_4, k_{p4}?))$$

$$\delta_{pumps} = \delta_p * (pamount(p_1, works) + pamount(p_2, works) + pamount(p_3, works) + pamount(p_4, works))$$

Operations for Normal State

SNormalBroken1

ΔSteamBoiler1

Input

ControlInput

AmountComputation

$z = \text{norm}$

$k_w = \text{broken}$

$k_d = \text{works}$

$s' = s + \text{amount} - d?$

$\delta' = \delta_{\text{pumps}} + \delta_d$

$s' \geq w_{\min} + \delta'$

$s' \leq w_{\max} - \delta'$

$s' < (w_{\min} + w_{\max})/2 \rightarrow \text{PumpsControlledOn}$

$s' \geq (w_{\min} + w_{\max})/2 \rightarrow \text{PumpsControlledOff}$

$v' = \text{closed} \wedge a' = \text{on}$

$z' = \text{broken}$

Complete Operation

$$\begin{aligned} \text{ControlNormal1} &\hat{=} && \text{SNormalFill1} \\ & && \vee \text{SNormalContinue1} \\ & && \vee \text{SNormalNotFill1} \\ & && \vee \text{SNormalWaterStop1} \\ & && \vee \text{SNormalControlStop1} \\ & && \vee \text{SNormalBroken1} \end{aligned}$$

Operations for Broken State

SBrokenContinue1

ΔSteamBoiler1

Input

ControlInput

AmountComputation

$z = broken$

$k_w = broken$

$k_d = works$

$s' = s + amount - d?$

$\delta' = \delta + \delta_{pumps} + \delta_d$

$s' \geq w_{min} + \delta'$

$s' \leq w_{max} - \delta'$

$s' < (w_{min} + w_{max})/2 \rightarrow PumpsControlledOn$

$s' \geq (w_{min} + w_{max})/2 \rightarrow PumpsControlledOff$

$v' = closed \wedge a' = on$

$z' = broken$

Operations for Broken State

SBrokenNormal1

ΔSteamBoiler1

Input

ControlInput

AmountComputation

$z = broken$

$k_w = works$

$w? \geq w_{min}$

$w? \leq w_{max}$

$w? < (w_{min} + w_{max})/2 \rightarrow PumpsControlledOn$

$w? \geq (w_{min} + w_{max})/2 \rightarrow PumpsControlledOff$

$s' = w?$

$v' = closed \wedge a' = on$

$z' = norm$

Operations for Broken State

SBrokenControlStop1

ΔSteamBoiler1

Input

ControlInput

z = broken

k_w = broken

k_d = broken

a' = off ∧ z' = stop

Operations for Broken State

SBrokenWaterStop1

ΔSteamBoiler1

Input

ControlInput

AmountComputation

$z = broken \vee z = norm$

$k_w = broken$

$k_d = works$

$s' = s + amount - d?$

$z = broken \rightarrow \delta' = \delta + \delta_{pumps} + \delta_d$

$z = norm \rightarrow \delta' = \delta_{pumps} + \delta_d$

$s' < w_{min} + \delta' \vee s' > w_{max} - \delta'$

$a' = off \wedge z' = stop$

Operations for Broken State

$$\begin{aligned} \text{ControlBroken1} &\hat{=} && \text{SBrokenContinue1} \\ & && \vee \text{SBrokenNormal1} \\ & && \vee \text{SBrokenControlStop1} \\ & && \vee \text{SBrokenWaterStop1} \end{aligned}$$

Complete Operation

$$\begin{aligned} \text{Control1} &\hat{=} && \text{ControlInit1} \\ & && \vee \text{ControlNormal1} \\ & && \vee \text{ControlBroken1} \end{aligned}$$